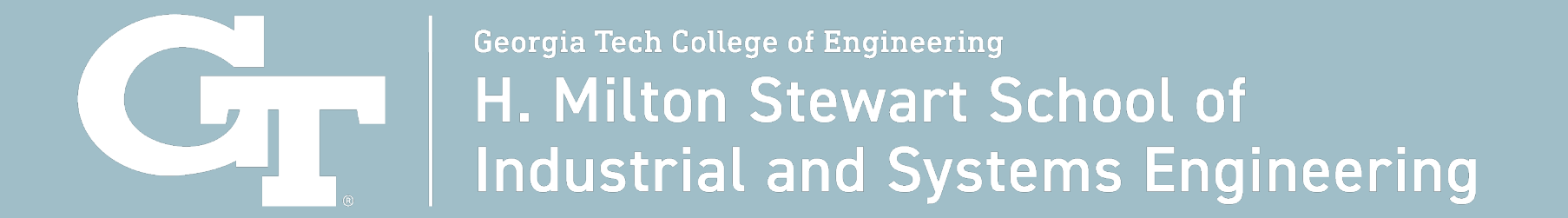


Comparative Analysis of Bisection-Based Methods for Solving Chance Constrained Programs

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Introduction

- Chance Constrained Program (CCP): Find the best decision whose probability of violating the uncertainty constraints is within a preset risk level

$$v^* = \min_{x \in X} \{c^T x : \mathbb{P}(\tilde{\xi}: g(x, \tilde{\xi}) \leq 0) \geq 1 - \varepsilon\}$$

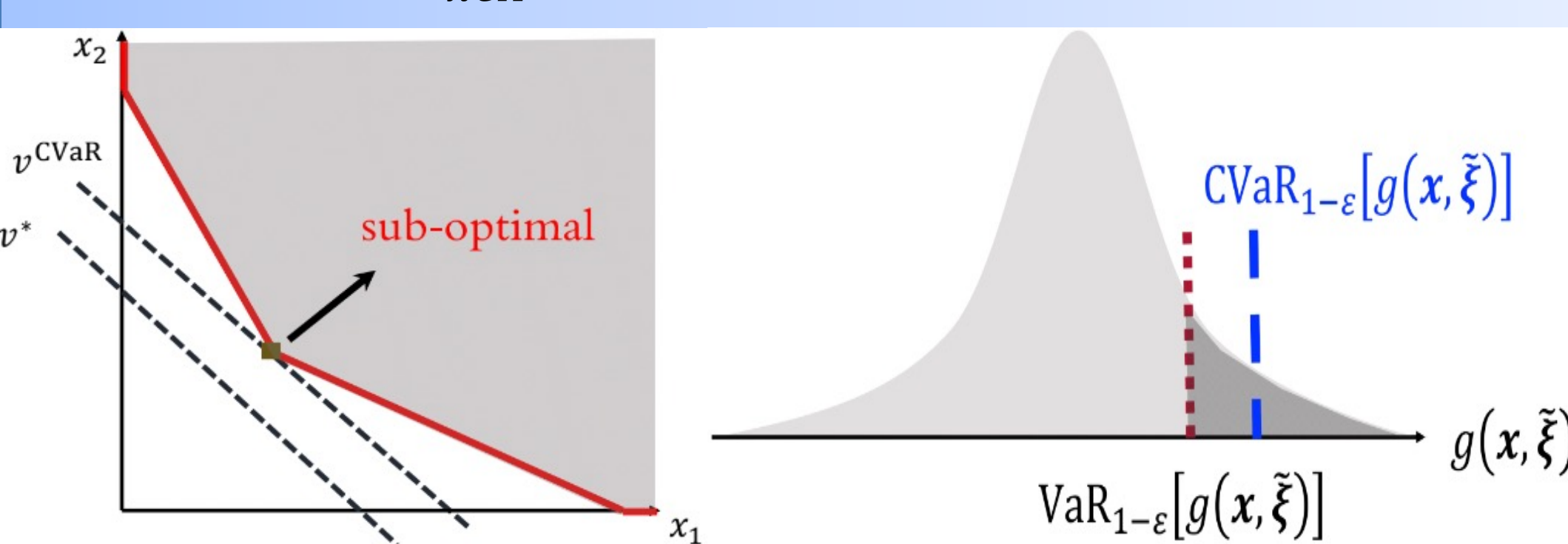
- Applications of CCP:



Portfolio Selection Wireless Networks

- One difficulty of CCP: The feasible region is non convex
- CVaR is known as the most effective convex approximation method

$$v^{CVaR} = \min_{x \in X} \{c^T x : CVaR_{1-\varepsilon}[g(x, \tilde{\xi})] \leq 0\}$$



Summary of Contributions

- New approximation methods are proposed to improve CVaR approximation

- Compare with DC approximation

Methods:

ALSO-X Sharp: Improvement by adjusting the upper bound of the CCP

Bisection-based Epsilon: Improvement by adjusting the epsilon of the CCP

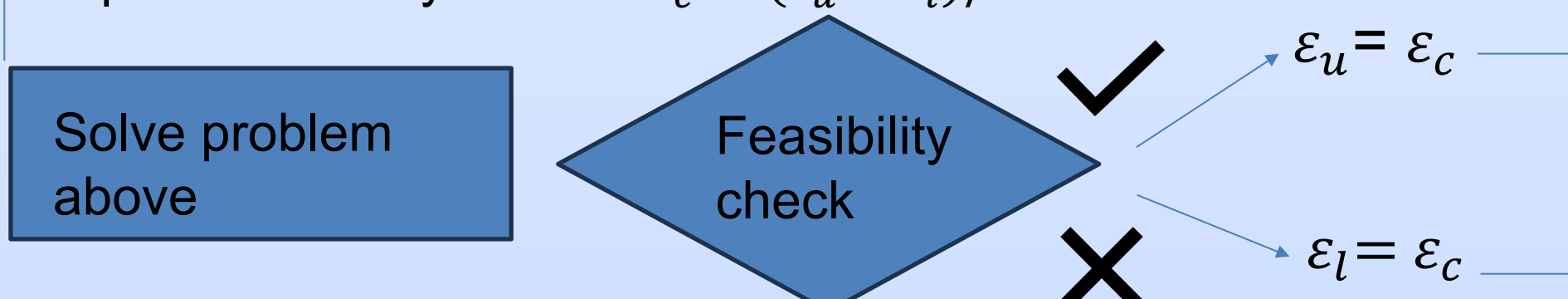
Bisection-based RHS: Improvement by adjusting the right-hand-side of the CCP

Approximation Methods

Bisection-based Epsilon:

$$x^* \in \operatorname{argmin}_{x \in X} \{c^T x : CVaR_{1-\varepsilon_c}[g(x, \tilde{\xi})] \leq 0\}$$

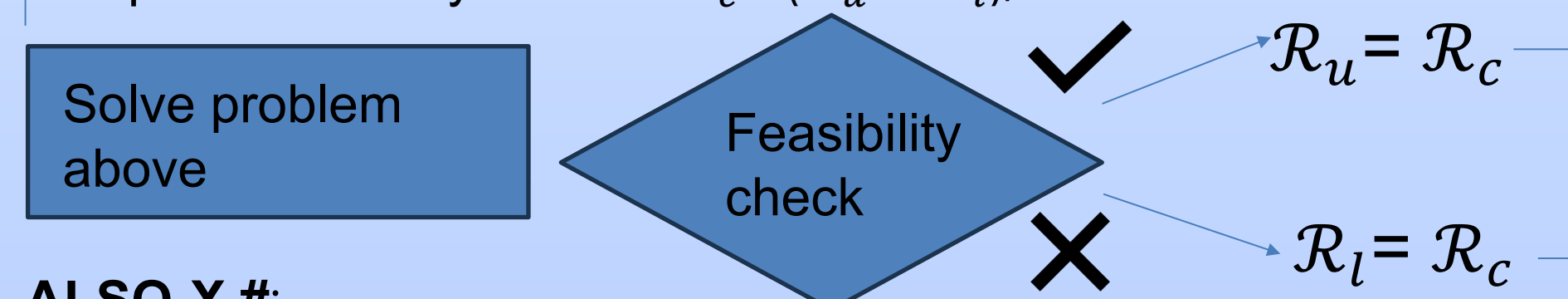
Repeat via binary search: $\varepsilon_c = (\varepsilon_u + \varepsilon_l)/2$



Bisection-based RHS:

$$x^* \in \operatorname{argmin}_{x \in X} \{c^T x : CVaR_{1-\varepsilon}[g(x, \tilde{\xi})] \leq \mathcal{R}_c\}$$

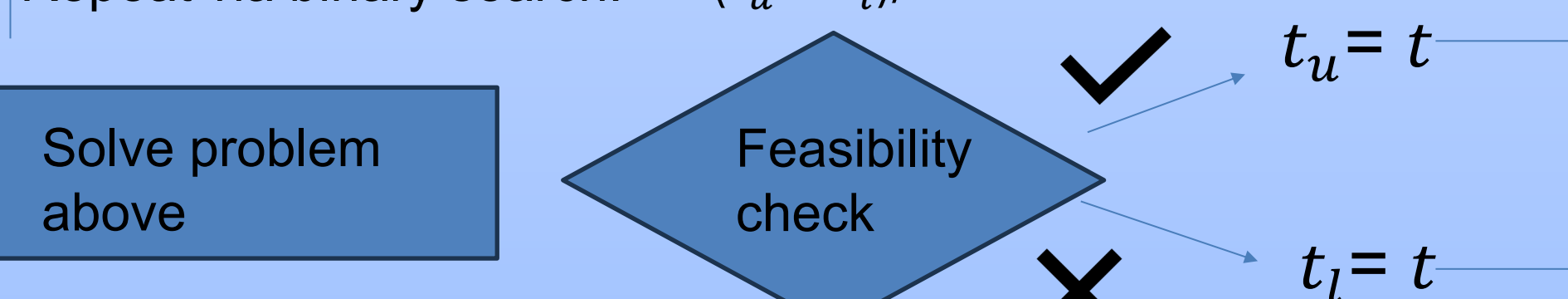
Repeat via binary search: $\mathcal{R}_c = (\mathcal{R}_u + \mathcal{R}_l)/2$



ALSO-X #:

$$x^* \in \operatorname{argmin}_{x \in X} \{CVaR_{1-\varepsilon}[g(x, \tilde{\xi})] : c^T x \leq t\}$$

Repeat via binary search: $t = (t_u + t_l)/2$



Numerical Comparison

Instance Name	CVAR			ALSO-X #			Bisection-based-RHS			Bisection-based-Epsilon		
	Epsilon value	Objective Value	Time (s)	Objective Value	Time (s)	Improvement (%)	Objective Value	Time (s)	Improvement (%)	Objective Value	Time (s)	Improvement (%)
1-7-5-3000-5	0.05	-17519.71	0.11 s	-17627.19	20.98	0.61%	-17626.27	30.95 s	0.61%	-17634.3	13.84 s	0.65%
	0.1	-17600.76	0.16 s	-17731.37	21.05s	0.74%	-17731.21	31.40 s	0.74%	-17750.89	14.34 s	0.85%
	0.15	-17657.97	0.18 s	-17824.63	21.41s	0.94%	-17824.5	31.60 s	0.94%	-17828.18	14.13 s	0.96%
	0.2	-17706.8	0.20 s	-17895.74	21.35 s	1.07%	-17895.78	32.66 s	1.07%	-17898.95	15.18 s	1.09%
	0.25	-17749.94	0.20 s	-17961.96	21.29s	1.19%	-17962.12	32.87 s	1.20%	-17965.65	15.33 s	1.22%
1-7-5-3000-2	0.05	-17511.49	0.09 s	-17629.33	21.06s	0.67%	-17629.16	31.58 s	0.67%	-17631.73	14.05 s	0.69%
	0.1	-17596.69	0.15 s	-17736.99	21.20 s	0.80%	-17736.99	31.73 s	0.80%	-17744.41	14.68 s	0.84%
	0.15	-17656.29	0.18 s	-17822.83	21.41s	0.94%	-17822.77	33.77 s	0.94%	-17822.23	14.97 s	0.94%
	0.2	-17705.5	0.17 s	-17896.01	21.32s	1.08%	-17896.15	31.72 s	1.08%	-17900.75	15.31 s	1.10%
	0.25	-17749.26	0.20 s	-17968.16	21.47 s	1.23%	-17968.39	32.75 s	1.23%	-17962.36	15.55 s	1.20%
1-7-5-3000-3	0.05	-17512.7	0.59s	-17608.9	21.58	0.55%	-17609.44	32.47 s	0.55%	-17623.47	14.86s	0.63%
	0.1	-17578.87	0.26s	-17720.15	22.40s	0.75%	-17720.75	32.58 s	0.76%	-17731.07	14.31s	0.81%
	0.15	-17648.55	0.15s	-17818.74	21.73s	0.96%	-17818.58	32.76 s	0.96%	-17820.15	14.59 s	0.97%
	0.2	-17698.94	0.15s	-17891.78	22.22s	1.09%	-17891.5	31.36 s	1.09%	-17889.61	14.80 s	1.08%
	0.25	-17741.75	0.19s	-17954.14	22.59s	1.20%	-17954.21	32.48 s	1.20%	-17957.43	15.95 s	1.26%
1-7-5-3000-4	0.05	-17495.494	0.16s	-17596.83	21.63s	0.58%	-17597.37	31.76 s	0.58%	-17606.92	15.07 s	0.64%
	0.1	-17578.57	0.19s	-17728.45	21.3s	0.85%	-17728.49	32.06 s	0.85%	-17748.885	13.98 s	0.97%
	0.15	-17643.55	0.32s	-17828.14	21.92 s	1.05%	-17828.44	31.70 s	1.05%	-17827.14	14.73 s	1.04%
	0.2	-17697.29	0.24s	-17901.14	21.28	1.15%	-17901.03	31.24 s	1.15%	-17902.49	15.09 s	1.16%
	0.25	-17741.93	0.20s	-17964.87	22.04 s	1.26%	-17964.99	31.61 s	1.26%	-17964.65	15.48 s	1.26%

Results

- RED=** Most optimal objective value. **YELLOW=** Quickest running time
- All three methods improve CVaR approximation
- About 90% of the time, **Bisection-based Epsilon** is the best

DC approximation

- These 4 methods can serve as the initial solutions for DC approximation, which is defined as

$$\min_{x \in X} \{c^T x : \frac{1}{\varepsilon} \mathbb{E}[g(x, \tilde{\xi}) + \varepsilon]_+ - \frac{1}{\varepsilon} \mathbb{E}[g(x, \tilde{\xi})]_+ \leq 0\}$$

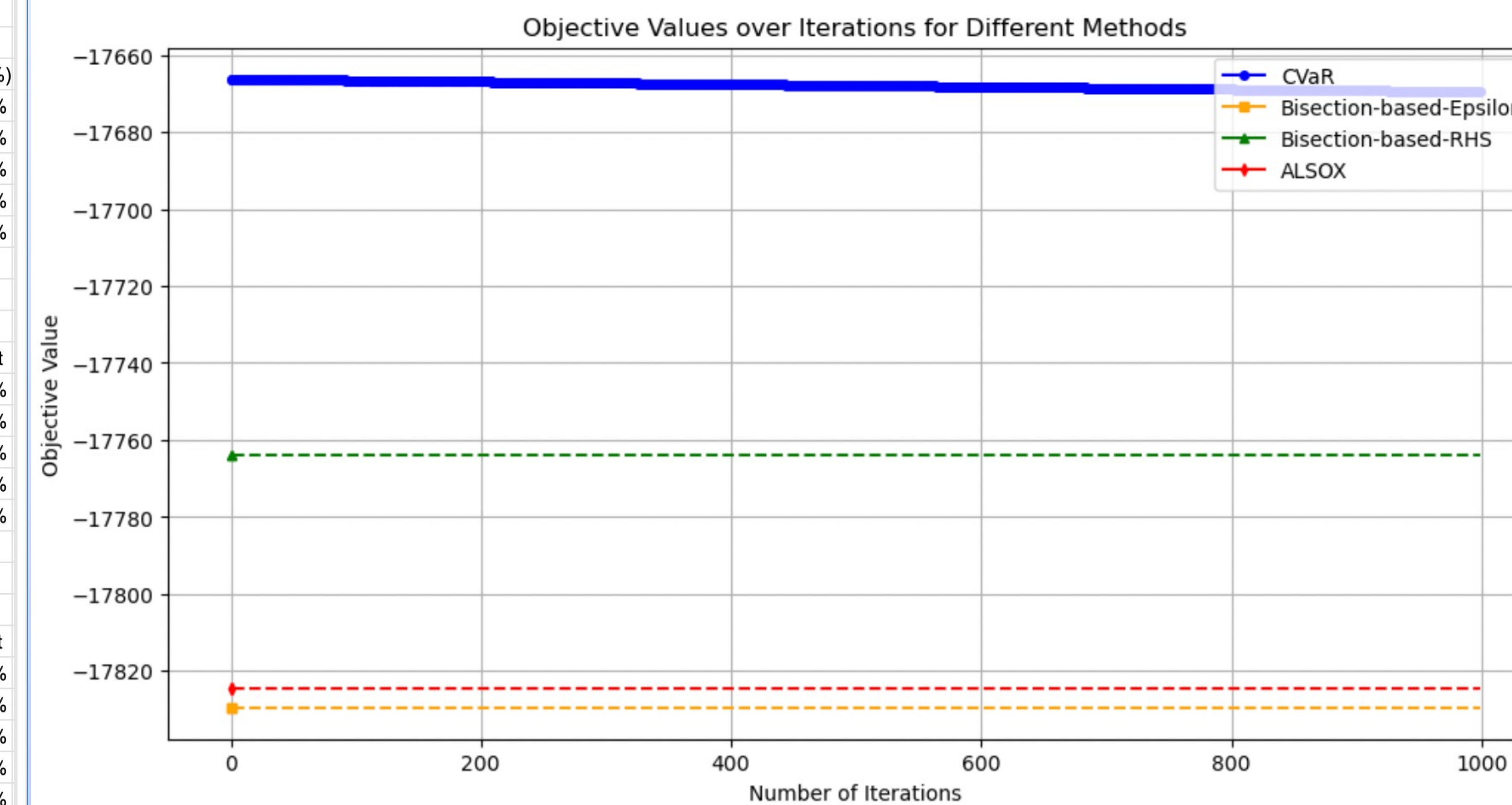
- After taking the derivative of the inner convex function, we follow a sub gradient-based algorithm to solve the DC approximation

$$\mathbb{E}[g(x, \tilde{\xi})]_+ \geq \mathbb{E}[g(x^{(0)}, \tilde{\xi})]_+ + \theta_{x^{(0)}} \mathbb{E}[g(x^{(0)}, \tilde{\xi})]_+ [x - x^{(0)}].$$

Summary

- Cvar approximation is employed to evaluate the potential losses in financial decision-making, serving as a critical tool for risk management. Investigating other methods that can improve CVaR, such as **Bisection-based Epsilon**, provides a more accurate estimate of potential extreme losses
- Under type ∞ - Wasserstein ambiguity set, **Bisection-based Epsilon** improves the CVaR approximation results 70% of the time across different epsilons and thetas over varying instances

Objective Values over Iterations for Different Methods



Initial Solutions

CVaR Approximation
Bisection-based Epsilon
Bisection-based RHS
ALSO-X#

Iterations

Instances were tested across varying numbers of iterations

Results

DC is deemed unnecessary for improving these initial solutions

Distributionally Robust Chance Constrained Programs

DRCCP's seek to determine optimal results that handle uncertain constraints and parameters, while taking into account all possible distributions in the Wasserstein ambiguity set.

$$v^* = \min_{x \in X} \{c^T x : \inf_{\mathbb{P} \in \mathcal{P}_\infty} \mathbb{P}(\tilde{\xi}: g(x, \tilde{\xi}) \leq 0) \geq 1 - \varepsilon\}$$

